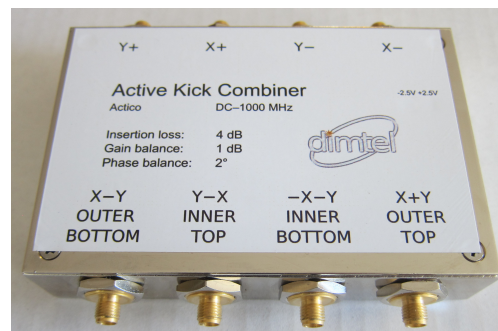




## Features

- DC–1000 MHz usable bandwidth
- 4 dB typical insertion loss
- 4° phase balance
- 1 dB gain balance
- SMA connectors

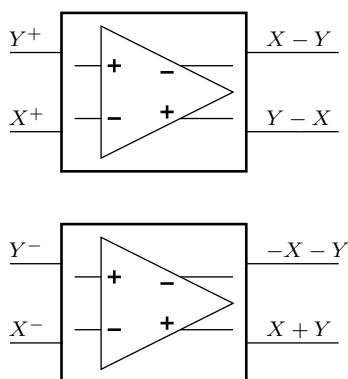


## Description

Actico is an 8 port active RF device for computing sums and differences of the input signals. It is designed for processing the differential outputs of horizontal and vertical bunch-

by-bunch feedback controllers. Actico generates appropriate drive signals for 4 diagonally located striplines. Closely matched responses of the individual channels the and wide bandwidth are optimized to maintain high bunch-to-bunch isolation.

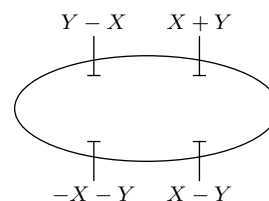
## Block Diagram



Actico is implemented using two wide-band differential amplifiers, as shown in the block diagram above. One of these amplifiers accepts  $X^+$  and  $Y^+$  signals and generates  $X-Y$  and  $Y-X$  drive outputs. The second amplifier converts  $X^-$  and  $Y^-$  into  $X+Y$  and  $-X-Y$  pair of outputs.

After high-power amplification, outputs

of Actico can be applied to the diagonal striplines as shown in the figure below.



## Electrical Specifications, +25°C

Parameter	Frequency	Units	Min	Typ	Max
Insertion loss <sup>1</sup>	DC–1.25 GHz	dB	—	7	10
Amplitude balance <sup>12</sup>	DC–1.25 GHz	dB	—	0.8	2
Phase balance <sup>13</sup>	DC–1.25 GHz	degree	—	3	10
VSWR <sup>4</sup>	DC–1.25 GHz	ratio	—	1.9	2
Upper 3 dB frequency <sup>5</sup>	—	MHz	1000	1150	—
Plane isolation, X or Y drive <sup>6</sup>	—	dB	30	38	—
Input voltage	—	mV	—	—	±500

<sup>1</sup>For two port measurements, six unused ports are terminated by 50Ω loads.

<sup>2</sup>Maximum insertion loss difference over a block-diagonal 4×4 S-parameter matrix.

<sup>3</sup>Computed over a block-diagonal 4×4 S-parameter matrix after excluding individual input and output delay errors.

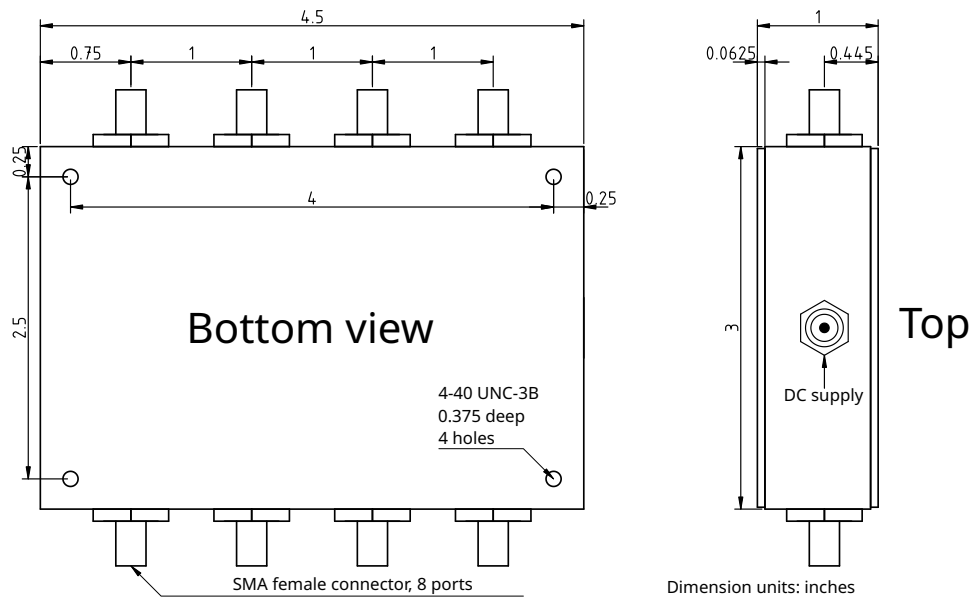
<sup>4</sup>For one port measurements ( $S_{11}$ ), seven unused ports are terminated by 50Ω loads.

<sup>5</sup>Relative to the DC gain

<sup>6</sup>See measurement approach description on page 4.



## Case outline



## Plane coupling test setup

### S-parameters

Actico is characterized by measuring 16 S-parameters as follows:

- Two  $2 \times 2$  forward transfer matrices between input and output ports;
- 8 reflection parameters (diagonal of the full scattering matrix);

### Forward transfer matrices

Two separate  $2 \times 2$  forward transfer matrices  $M^+$  and  $M^-$ . Matrix  $M^+$  is defined in Eq. 1, and matrix  $M^-$  — in Eq. 2. These are measured two ports at a time, with six unused ports terminated by Mini-Circuits ANNE-50L+  $50\Omega$  loads.

$$\begin{bmatrix} Y - X \\ X - Y \end{bmatrix} = M^+ \begin{bmatrix} X+ \\ Y+ \end{bmatrix} = \begin{bmatrix} S_{Y-X}^{X+} & S_{X-Y}^{X+} \\ S_{Y-X}^{Y+} & S_{X-Y}^{Y+} \end{bmatrix} \begin{bmatrix} X+ \\ Y+ \end{bmatrix} \quad (1)$$

$$\begin{bmatrix} -X - Y \\ X + Y \end{bmatrix} = M^- \begin{bmatrix} X- \\ Y- \end{bmatrix} = \begin{bmatrix} S_{-X-Y}^{X-} & S_{X+Y}^{X-} \\ S_{-X-Y}^{Y-} & S_{X+Y}^{Y-} \end{bmatrix} \begin{bmatrix} X- \\ Y- \end{bmatrix} \quad (2)$$

In order to facilitate the analysis of this data, phase response measurements are processed as follows. For each element of the matrix, group delay is estimated by a linear fit to the phase data in the 0.3–1250 MHz range. Average delays for  $M^+$  and  $M^-$  are subtracted. Maximum delay error between all 8 forward paths is calculated and reported in the factory test results. For the path-to-path phase error analysis phase values for the inverting paths in  $M_{\text{fwd}}$  are offset by  $180^\circ$ .

### Calculated plane-to-plane coupling

From the S-parameter matrices it is possible to calculate the transfer functions for horizontal and vertical input signals to horizontal and vertical kicks (assuming perfectly balanced diagonal striplines and power amplifiers).

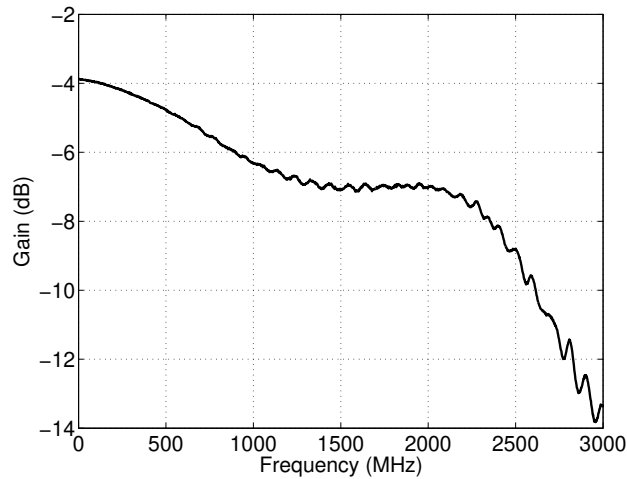
$$\begin{bmatrix} H_{xX} \\ H_{xY} \\ H_{yY} \\ H_{yX} \end{bmatrix} = \begin{bmatrix} S_{-X-Y}^{X-} + S_{X-Y}^{X+} - S_{Y-X}^{X+} - S_{X+Y}^{X-} \\ S_{-X-Y}^{X-} + S_{Y-X}^{X+} - S_{X-Y}^{X+} - S_{X+Y}^{X-} \\ S_{-X-Y}^{Y-} + S_{Y-X}^{Y+} - S_{X-Y}^{Y+} - S_{X+Y}^{Y-} \\ S_{-X-Y}^{Y-} + S_{X-Y}^{Y+} - S_{Y-X}^{Y+} - S_{X+Y}^{Y-} \end{bmatrix} \quad (3)$$

where  $H_{xX}$  and  $H_{xY}$  are responses from the horizontal input to horizontal and vertical kicks respectively. Similarly,  $H_{yY}$  and  $H_{yX}$  are responses from the vertical input to vertical and horizontal kicks.

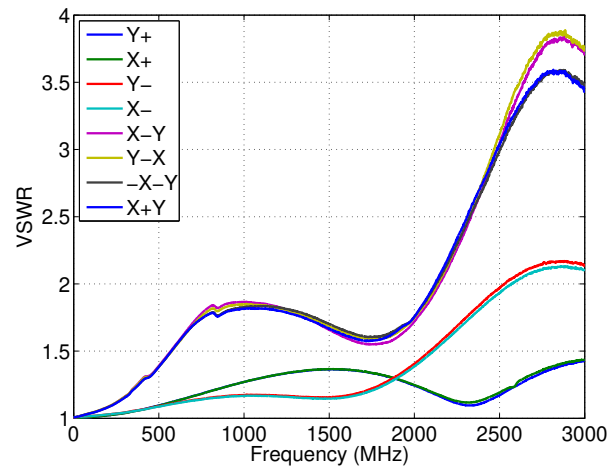


## Typical performance curves

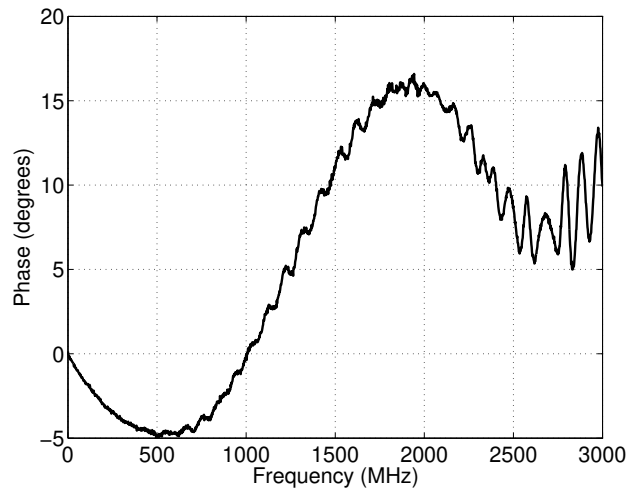
### Forward gain



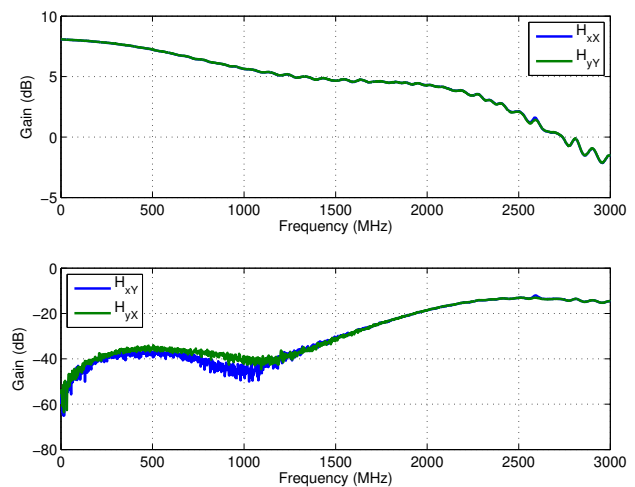
### VSWR



### Forward phase<sup>1</sup>



### In-plane responses and coupling terms



<sup>1</sup>port delays removed

## Typical performance curves (continued)

Cross-plane isolation

